Amendments to the Abstract:

Abstract of the Disclosure

In the-cleaning using the <u>a</u> self-propelled cleaning device, firstly the cleaning device moves alongside the <u>a</u> wall surface and then a reference direction is set.

Next, the cleaning device advances alongside the wall surface <u>by at a prescribed</u> distance, makes a right-angle turn, and travels in the reference direction. When the cleaning device reaches the surface of the <u>an</u> opposing wall, it moves in a spiraling manner. At that time, the orientation angle of the cleaning device, <u>which is</u> estimated using a gyro sensor, is checked and corrected. If an obstacle is encountered while traveling, the cleaning device travels on a path that avoids the obstacle or travels in a spiral manner in a region in front of the obstacle.